

What is Physics?

Model the physical
universe.
(not spiritual)

Simplest model

↑
visualise
understand

00 make predictions
00

4 Mathematical models

1 2 3 4 Laws
1+2=3

Observation → quantities

Things have different position

x



+

Can quantify position by
measuring the distance from me.

Need a fixed point

And a Unit of measurement.

— This must be the same
for everyone

e.g. - Meter

Defined in ^{terms} of the
speed of light in a vacuum

speed of light $\sim 3 \times 10^8 \text{ m/s}$

1 meter - distance travelled
in $\frac{1}{3 \times 10^8} \text{ s}$

Time event

The difference between
two events that take place
at the same position.

Measurement

Based on regularly occurring
events

- Sun 14
- moon 1
- dripping water 10,000
- pendulum 20,000



Unit - second

Based on a certain number
of oscillations of the radiation
from some Caesium isotope.

4 Dimensions

3 position

1 time

To define position we need

3 distances. N-S
E-W
up-down.

Motion

\vec{x}
B

\boxed{x}
A

Defining movement.
use position and time

Distance travelled - how far the
box moves.



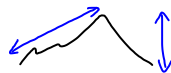
Displacement Distance travelled
in a particular direction



We can see that distance and
displacement are different quantities

distance - size

displacement - size and direction



All quantities either have
size only or size and direction

vector - size + direction ← displacement

scalar - size

time
distance

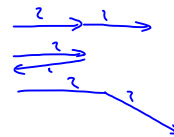
Scalar - time, distance

Represented by a number

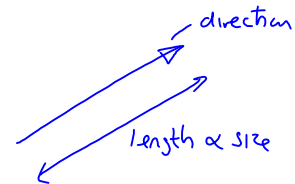
- they add
- subtract

Vector

$2 + 2$ not always 4



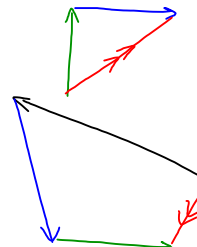
represented by Arrows



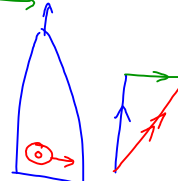
Adding Vectors

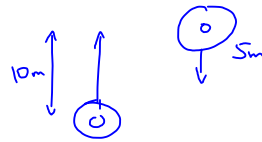
Arrange nose - tail

resultant is the line joining the
free tail - free nose



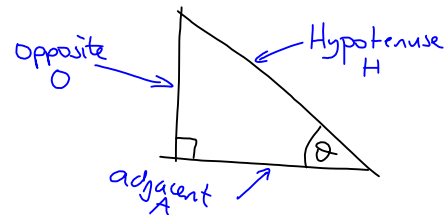
Example





When we add perpendicular vectors we get right angled triangles.

Trigonometry



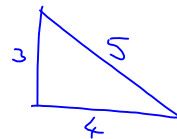
$$\sin \theta = \frac{O}{H} \quad O = H \sin \theta$$

$$\cos \theta = \frac{A}{H} \quad A = H \cos \theta$$

$$\tan \theta = \frac{O}{A}$$

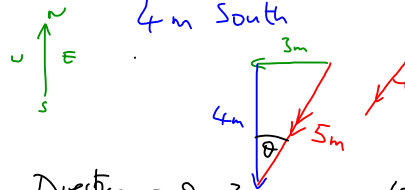
Pythagoras

$$H^2 = O^2 + A^2$$



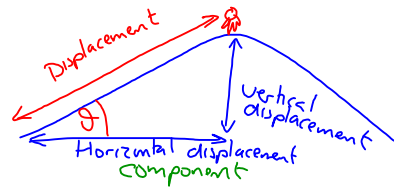
Example

walk 3m W then
4m South



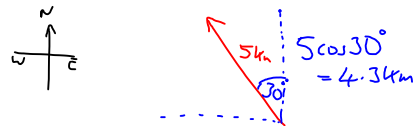
Direction $\sin \theta = \frac{3}{5}$ $\text{Inv. sin} \left(\frac{3}{5} \right) =$
 $\theta = 36.9^\circ$

Taking components (Resolving)



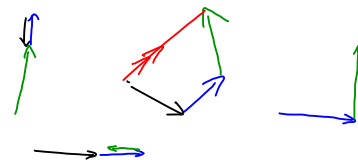
$$\begin{aligned} \cos \theta &= \frac{A}{R} \\ A &= R \cos \theta \end{aligned} \quad \begin{aligned} \sin \theta &= \frac{O}{R} \\ O &= R \sin \theta \end{aligned}$$

Example If you walk 5km
30° to the W of N. How
far N will you travel?

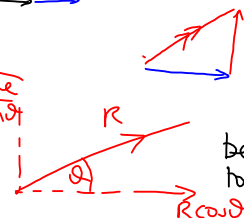


We will always take components
in convenient h directions
e.g. vertical & horizontal

Why? - Makes adding
vectors easier.



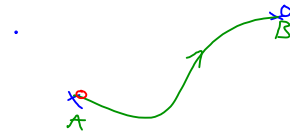
Note
 $R \sin \theta$



becos it's next
to the angle

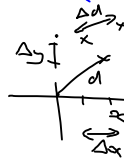
Speed

We observe that the time taken from A to B varies for different bodies.



$$\text{Average Speed} = \frac{\text{distance}}{\text{time}} = \frac{\Delta d}{\Delta t}$$

(how fast)



$\Delta \Rightarrow$ difference

Unit - meter/sec

scalar m/s ms^{-1}

Example

Flekkre \rightarrow Bergen
time - 3hrs / 50km

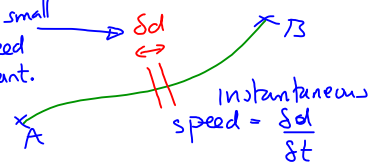
$$\text{Speed} = 50 \text{ km/hr}$$

$$\frac{50000}{3600} \approx 14 \text{ m/s}$$

Instantaneous speed

Speed at an instant

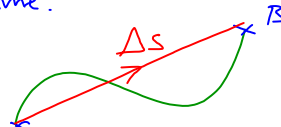
Step so small that speed is constant.



Note If speed constant
t = average

Velocity

Displacement per unit time.




average velocity = $\frac{\Delta s}{\Delta t}$



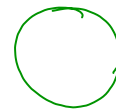
If $\Delta s = 0$ then $v = 0$

Instantaneous velocity



$v = \frac{\delta s}{\delta t}$

δs - so small that speed and direction - constant

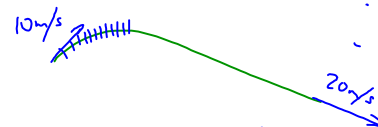


30 km/hr

- velocity not constant
- direction changing.

Acceleration (a)

Rate of change of velocity



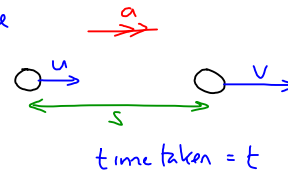
Average accel. = $\frac{\Delta v}{\Delta t}$



Motion with constant acceleration

— in a straight line

Example



Motion in 1 Dimension

Displacement

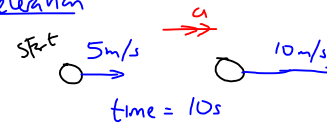


Direction is given by the sign.

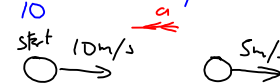
Velocity



acceleration



$$a = \frac{10 - 5}{10} = +0.5 \text{ m/s}^2$$



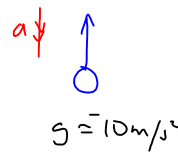
$$a = \frac{5 - 10}{10} = -0.5 \text{ m/s}^2$$



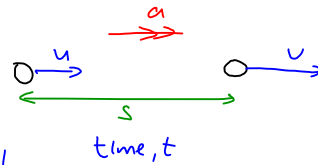
$$a = \frac{-10 - (-5)}{10} = -0.5 \text{ m/s}^2$$



$$a = \frac{-5 - (-10)}{10} = +0.5 \text{ m/s}^2$$



Equations of motion with constant acceleration



u - initial
 v - final

From definition $a = \frac{v-u}{t}$ ①

average velocity $= \frac{u+v}{2} = \frac{s}{t}$

$\Rightarrow s = \left(\frac{u+v}{2}\right)t$ ②

from ① - $t = \frac{v-u}{a}$

Substitute into ②

$$s = \left(\frac{u+v}{2}\right)\left(\frac{v-u}{a}\right)$$

$$s = \frac{v^2 - u^2}{2a}$$

$v^2 = u^2 + 2as$ ③

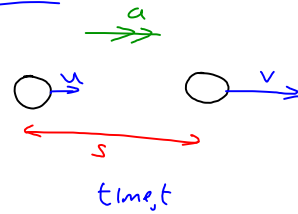
Also from ① $v = u + at$

substitute into ②

$$s = \left(\frac{u+v}{2}\right)t \quad s = \left(\frac{u+u+at}{2}\right)t$$

$$= ut + \frac{1}{2}at^2$$

Suvat



$$a = \frac{v-u}{t}$$

$$s = \left(\frac{u+v}{2}\right)t$$

$$s = ut + \frac{1}{2}at^2$$

$$v^2 = u^2 + 2as$$

example

Free Fall

- ignore air resistance
 $a = -10 \text{ m/s}^2$

Example

1. A body is thrown up

with a velocity of 50 m/s

What is its displacement after 3 s ?

$s = ?$

$u = 50 \text{ m/s}$

$v =$

$a = -10 \text{ m/s}^2$

$t = 3 \text{ s}$

$$s = ut + \frac{1}{2}at^2$$

$$= 50 \cdot 3 - \frac{1}{2} \cdot 10 \cdot 3^2$$

$$= 105 \text{ m}$$

After 15 s ?

$$s = 50 \cdot 15 - \frac{1}{2} \cdot 10 \cdot 15^2$$

$$= -375$$



Graphical representation of motion

$$a \text{ or } \frac{v-u}{t}$$

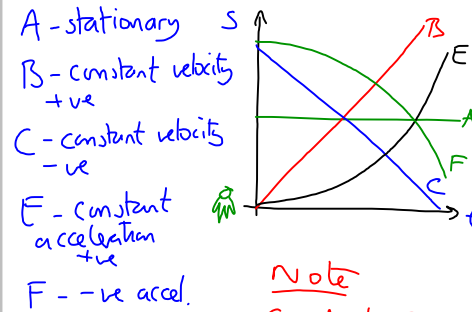
Displacement - time

velocity - time

acceleration - time

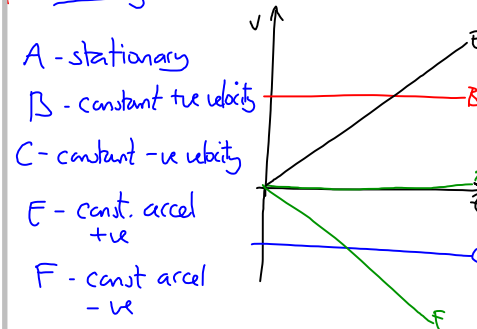
Phet

Displacement - time



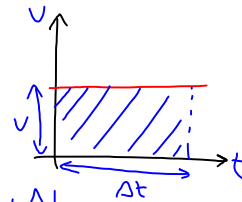
Note
 Gradient of s-t
 graph = velocity
 $v = \frac{\Delta s}{\Delta t} \quad \left(v = \frac{ds}{dt} \right)$

velocity - time



Note
 Gradient = accel.
 $= \frac{\Delta v}{\Delta t} \quad \left(\frac{dv}{dt} \right)$

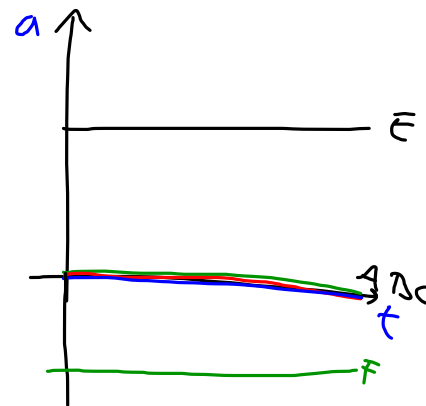
Area under graph



$$\text{Area} = v \Delta t$$

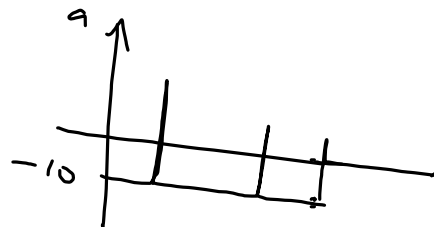
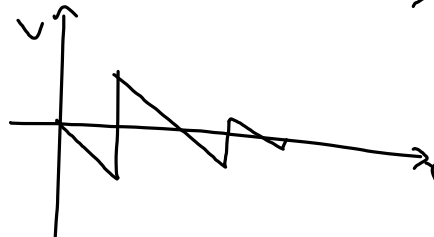
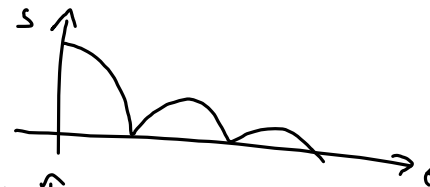
$$\text{but } v = \frac{\Delta s}{\Delta t} \Rightarrow v \Delta t = \Delta s$$

acceleration - time



Example

Bouncing ball



We can now model motion but what causes it?

To move a body it must be pushed or pulled.

Force (F)

– Push or a Pull

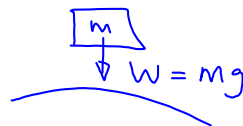
unit – Newton (N)

Vector

Examples

Weight

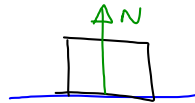
Force towards the centre of the Earth



– Weight acts at the centre of a body.

Normal Force (N)

The force acting perpendicular to two touching surfaces

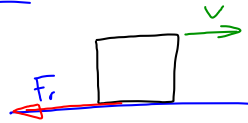


Tension (T)

When the force is exerted with a string



Friction



opposes the relative motion
between two touching surfaces

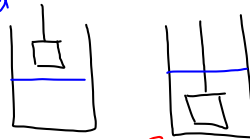
depends upon - Normal force
- Surfaces

$$F_r = \mu N \quad \mu - \text{coefficient of friction}$$

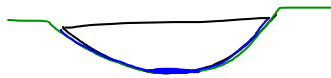
Upthrust - buoyancy

- Archimedes

When a body is immersed
in a fluid it experiences an upward
force equal to the weight of fluid
displaced



Note: volume displaced = volume
of object

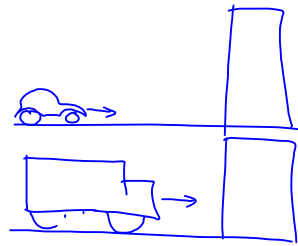


Air Resistance

Opposes motion of bodies
through the air

Depends upon - shape
- speed

Consider this



When determining the force required to stop these bodies we must consider Mass and velocity

Momentum = Mass \times velocity

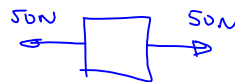
- Vector
- unit kg m/s
 Ns

Newton's Laws of Motion

Newton 1st Law

A body will remain at rest or moving with constant velocity unless acted upon by an unbalanced force.

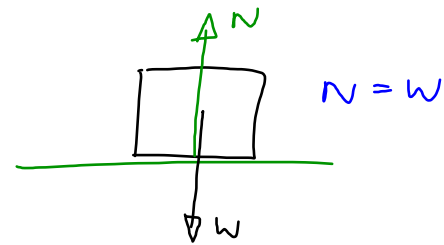
What is an unbalanced force?



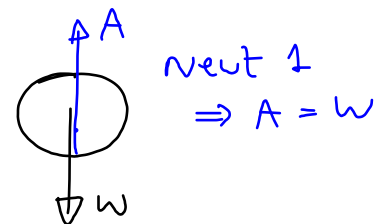
balanced \Rightarrow resultant = 0N



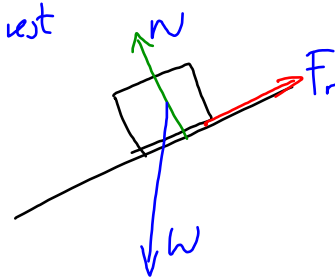
Box at rest \Rightarrow forces balanced



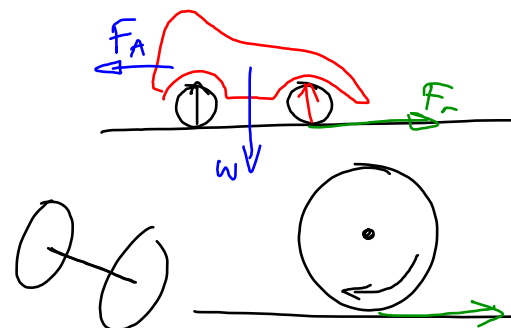
ball falls with constant velocity



Box at rest



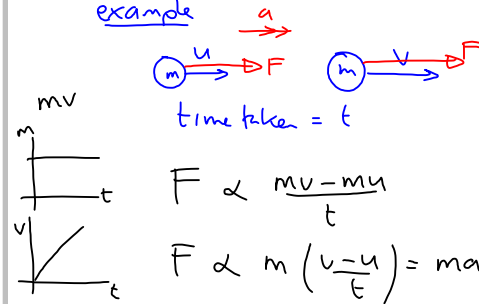
Car accelerates along the road



Newton's 2nd Law

The rate of change of momentum of a body is directly proportional to the unbalanced force and takes place in the same direction.

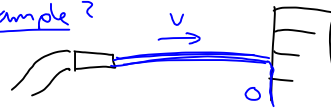
example



If F - Newtons
 m - kg
 u, v - m/s
 constant = 1

$$\boxed{F = ma}$$

example 2



newt 1 - water experiences F

newt 2 - Force experienced by water = rate of change of momentum

mv

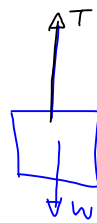
= mass per unit time \times change in velocity

Two graphs are shown: a velocity-time graph (v vs t) showing a constant value, and a mass-time graph (m vs t) showing a linear increase. The rate of change of momentum is given by $\frac{d(mv)}{dt}$ or $v \frac{dm}{dt}$.

Examples

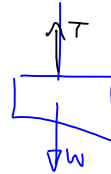
$$\frac{\Delta mv}{\Delta t}$$

①



Newton 1
forces unbalance
 $T > w$

Newton 2
 $T - w = ma$
 $T = ma + w$



$w - T = ma$
 $T = w - ma$

If $T = 0$

$$0 = w - ma$$

$$w = ma$$

$$mg = ma$$

$$g = a$$

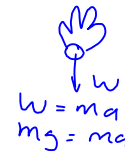
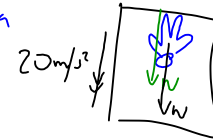
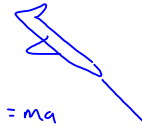


$$w - n = ma$$

$$w = ma$$

$$mg = ma$$

$$g = a$$

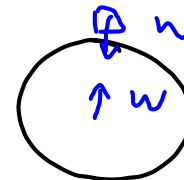
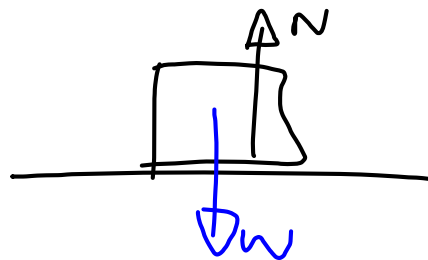


$$w = ma$$

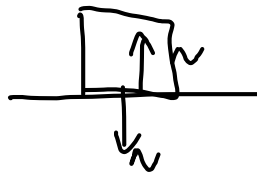
$$mg = ma$$

Newton's 3rd Law

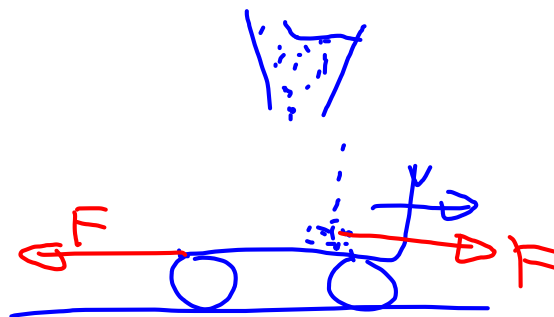
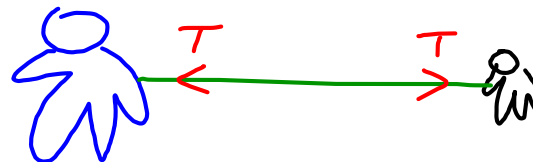
If body A exerts a force on body B then body B exerts an equal and opposite force on A.



earth pulls box down \Rightarrow
box pulls earth up.



Spacemen



Title
Introduction

Method (copy + paste)

Diag. (copy)

Results

L_m	t_s
10	2.6
10	2.7
10	2.5
10	2.6

- Table
 - include raw data
 - uncertainties
 - units
- show when form.

length ± 0.01			

Uncertainties

- $\frac{1}{2}$ smallest division
 $\pm 0.5 \text{ mm}$.

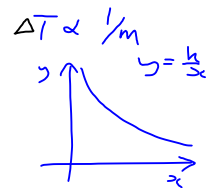
Use judgement -

1 sf

repeated measurement



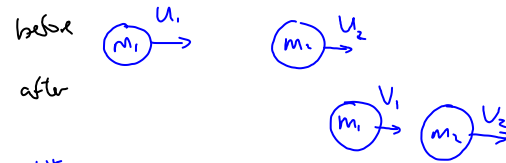
$$y = mx + c$$



$$y = \frac{k}{x}$$



Collision



1st Law - When they hit both balls experience an unbalanced force

2nd Law - size of force = rate of change of momentum

If collision lasts Δt seconds

then change of momentum = $\frac{m_1 v_1 - m_1 u_1}{\Delta t}$ for ball (1)

for ball (2) = $\frac{m_2 v_2 - m_2 u_2}{\Delta t}$

Newt 3 $\frac{m_1 v_1 - m_1 u_1}{\Delta t} = - \frac{m_2 v_2 - m_2 u_2}{\Delta t}$

$$m_1 v_1 - m_1 u_1 = -m_2 v_2 + m_2 u_2$$

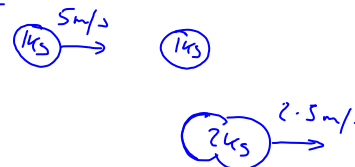
$$m_1 u_1 + m_2 u_2 = m_1 v_1 + m_2 v_2$$

Conservation of momentum

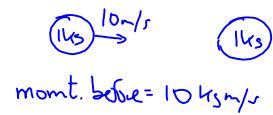
Momentum at start = momentum at the end.

For a group of isolated bodies
total momentum = constant.

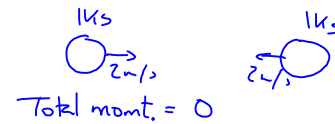
Example



Example 2



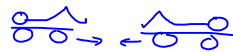
Consider this:



Newton's Law \rightarrow all are possible but we can't predict which will happen

- The last example we know can't happen. The balls would have to push each other hard

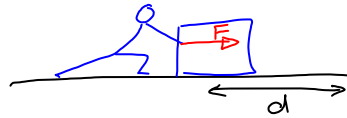
- What enables one ball to push another?



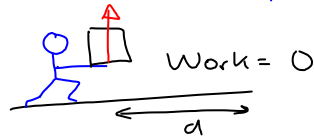
ENERGY

WORK

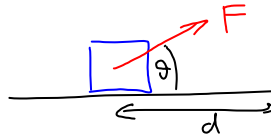
When a force moves its point of application in the direction of the force, WORK IS DONE.



$$\text{Work done} = F \times d$$



$$\text{Work} = 0$$



$$\text{Work} = F \cos \theta \cdot d$$

Energy

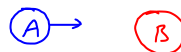
Energy is the quantity that is transferred when work is done.

If A does work on B
energy is transferred from A → B

Body A must have energy if it is to push B.

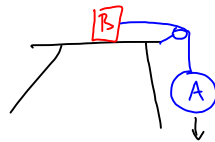
There are two ways that A can have energy.

① Because it's moving



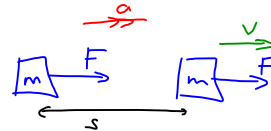
Kinetic Energy





Potential Energy
- Energy due to Position

KE



$$F = ma$$

$$WD = Fs = KE$$

$$v^2 = u^2 + 2as = mas$$

$$v^2 = 2as$$

$$as = \frac{1}{2}v^2$$

$$KE = \frac{1}{2}mv^2$$

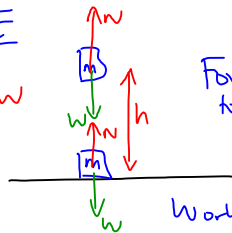
Note we have assumed energy is conserved. If this isn't true then we can't solve any problems.

Law of Conservation of Energy

Energy can not be created or destroyed.

PE

$$N = W$$

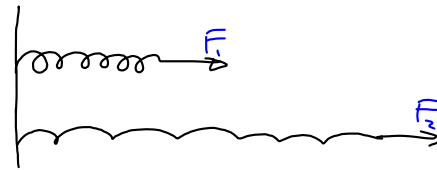


Force required to lift body
 $= mg$

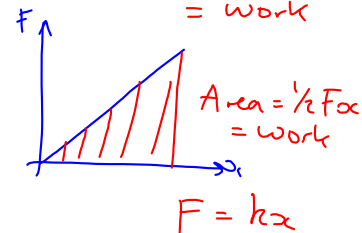
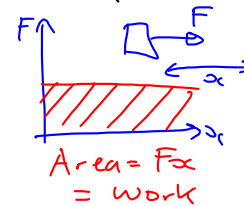
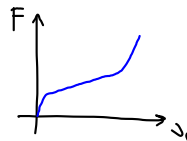
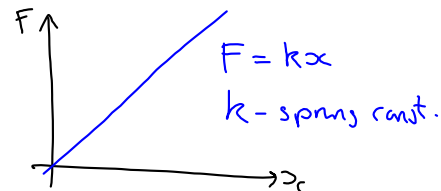
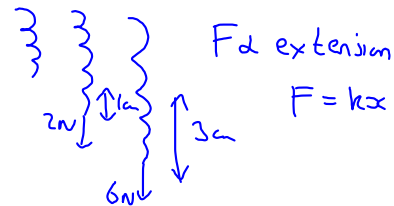
$$\text{Work done} = mgh$$

$$\therefore \text{Increase in PE} = mgh$$

This is the only form of PE



When a string is stretched
the force required gets bigger
for a simple spring $F \propto x$



$F = kx$
 $w = \frac{1}{2} kx^2$
Elastic PE

Conservation of Energy

Diagram: A ball is shown at two positions. At the top position, it is labeled 'PE' and 'KE+PE'. At the bottom position, it is labeled 'KE'. A dashed arrow points from the top position to the bottom position.

$$\Delta KE = \Delta PE$$
$$\left(\frac{1}{2}mv^2 - 0\right) = mgh - 0$$
$$\frac{1}{2}mv^2 = mgh$$
$$\frac{1}{2}v^2 = gh$$
$$v^2 = u^2 + 2as$$
$$0 = v^2 - 2gh$$

Power

Work done per unit time

unit - Watt (W)
scalar

High power \Rightarrow can do work
in a short time

Car \Rightarrow Fuel \rightarrow KE ($\frac{1}{2}mv^2$)
powerful car will accelerate
fast.

Elastic + Inelastic collisions

Elastic collision

KE and momentum are
conserved



Cons. of mom't
 $mu = mv_1 + mv_2$
 $u = v_1 + v_2$

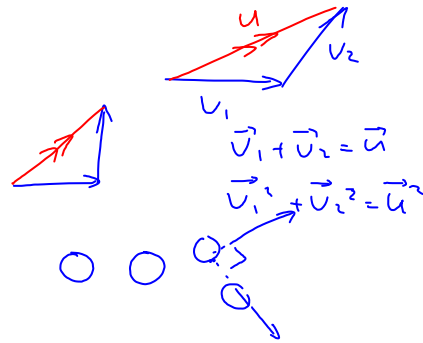


cons. of KE

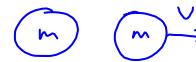
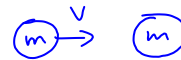
$$\frac{1}{2}mu^2 = \frac{1}{2}mv_1^2 + \frac{1}{2}mv_2^2$$

$$u^2 = v_1^2 + v_2^2$$

$$\Rightarrow \text{either } v_1 = 0 \text{ or } v_2 = 0$$



The simplest case
elastic

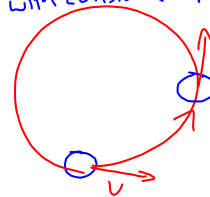


completely inelastic



Motion in a circle

Consider a body moving in a circle
with constant speed.



We can see
that velocity
is not constant
Since direction is
changing

Newton 1 \Rightarrow unbalanced force

Direction of force - same as direction
of acceleration

$a = \frac{\text{change in velocity}}{\text{time}}$
 $\text{time} = \frac{\text{final } v - \text{initial } v}{\Delta t}$

time from $A \rightarrow B = \Delta t$
 $a = \frac{\Delta v}{\Delta t}$
 change in velocity from $A \rightarrow B$
 The direction of a is towards the centre

Magnitude of accel.
 $a = \frac{v^2}{r}$

centripetal acceleration
 $\Rightarrow \text{centripetal force} = ma$
 $= \frac{mv^2}{r}$

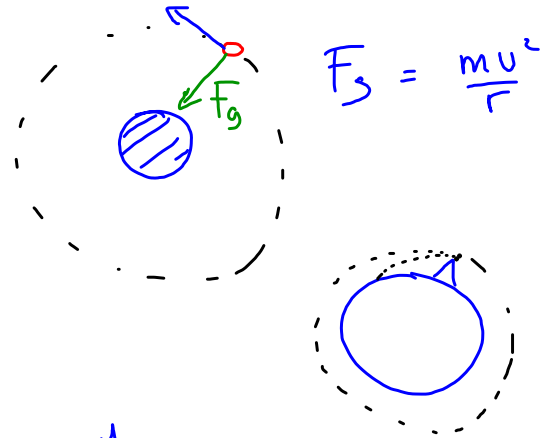
Example
 mass on a string

centripetal F is Tension
 $T = \frac{mv^2}{r}$

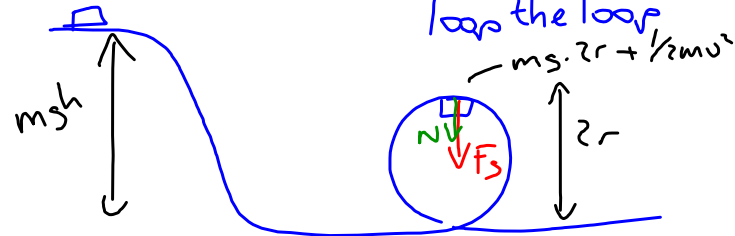
Note Newton 3 \Rightarrow person holding other end of rope will experience an opposite force

Example?
 Car on a circular track

Satellite



Fairground



$$F_g + N = \frac{mv^2}{r}$$

$$\text{If } N = 0 \quad F_g = \frac{mv^2}{r}$$

→ minimum speed

